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Hierarchical Graphs for Graph Grammars (Extended Abstract) - Michael Himsolt (Correct)
of nodes, and .By explicit declaration of **hierarchy levels**. Representations of the graph where
nodes, and .By explicit declaration of **hierarchy levels**. Representations of the graph where parts of the
above open or below closed are invisible. Among any **path** from a root to a leaf in T, there may be at most
www.fmi.uni-passau.de/archive/archive.theory/ftp/graphed/papers/HGraph.ps.gz

The Web and Exerquiz Packages - Manual of Usage - Story (1999) (Correct)
option The latextoc option 2.4. **Navigational** Aids A **Navigational Bar** Direction
option 2.4. **Navigational** Aids A **Navigational Bar** Direction Icons 3. The Exerquiz Package 3.1.
Packages Manual of Usage D. P. Story Directory **Tab**le of Contents. Begin Article. Copyright c
online.redwoods.cc.ca.us/instruct/darnold/StaffDev/Workshop/webeqman.pdf

The Web and Exerquiz Packages Manual of Usage - Story (1999) (Correct)
2.3.4 The latextoc option .6 2.4 **Navigational** Aids .6 2.4.1 A
Aids .6 2.4.1 A **Navigational Bar** .6 2.4.2 Direction Icons
Last Revision Date: May 5, 1999 Version 1.00 2 **Tab**le of Contents 1 Introduction 3 2 The Web Style
online.redwoods.cc.ca.us/instruct/darnold/StaffDev/Workshop/p_webeqman.pdf

Metaclass Composability - Bouraqadi-Saadani, Ledoux, Rivard (Correct)
Suppose A implements a foo method that sends **bar** to the class of the receiver. When foo is sent to
with its sole instance (i.e.a class)ffl the **hierarchy** of the metaclasses is parallel to the **hierarchy**
is organized into an architecture of several (meta)**levels** of abstraction. Each (meta)**level** describes and
ftp.emn.fr/pub/objet/publications/ecoop96.ps.gz

On Partitioning Dynamic Adaptive Grid Hierarchies - Manish Parashar (1996) (Correct) (22 citations)
of the DAGH in 5 such snapshots are listed in **Tab**le 1. Efficiency at a grid **level** refers to the
and loadbalancing of the adaptive grid **hierarchy** to be performed cost-effectively. The run-time
of logical locality, both across different **levels** of the **hierarchy** under expansion and contraction
www.cs.utexas.edu/users/dagh/./Papers/hicss.ps

Optimizing Metalization Patterns For Yearly Yield - Burgers Eikelboom Netherlands (Correct)
that we arrive for yearly optimization at fewer bus **bars** and a much lower number of fingers. The total
with in the next two subsections. Resistive losses **Tab**le 1 presents a compact overview of the different
can be optimized for specific other illumination **levels**. In this paper we show that optimization for a
ftp.ecn.nl/pub/www/library/conf/ieee97/patterns.pdf

Near-Critical Path Analysis of Program Activity Graphs - Alexander, al. (1994) (Correct) (1 citation)
Computer, pp. 63-75, Sept. 1990. 22] D. Bailey, J. **Bar**ton, T. Lasinski, and H. Simon, ed.The
near-critical **path** algorithms are summarized in **Tab**le I. **TABLE** I Worst-case complexities of
descriptions of run-time events. IPS provides a **hierarchy** of statistical information based on a five
www.erc.msstate.edu/thrusts/ca/html/../publications/MASCOTncp.ps.gz

A Hierarchy of Qualitative Representations for Space - Kuipers (1996) (Correct) (16 citations)
(QR-96) Menlo Park, CA: AAAI Press, 1996. A **Hierarchy** of Qualitative Representations for Space
foundation, and each abstracted from the **levels** below it. At the control **level**, the robot and its
abstracted to a topological network of places and **paths**. Local metrical models, such as occupancy grids,
ftp.cs.utexas.edu/pub/qsim/papers/Kuipers-qr-96.ps.Z

Hierarchical Hybrid Control: a Case Study - Godbole, Lygeros, Sastry (1994) (Correct) (8 citations)
given the current technology. They are summarized in **tab**le 3.1. **Tab**le 1: Constraints on Actuators and
of the plant model are used at each layer of the **hierarchy**. In the bottom layer the plant model is usually
arranged in two (or more) layers [3, 4]Different **levels** of abstractions of the plant model are used at
robotics.eecs.berkeley.edu/~godbole/case.ps

Specifying Navigational Transformations in Hypermedia. A.. - Mere, Rossi (1996)   (Correct)
1 Specifying **Navigational** Transformations in Hypermedia. A temporal
We are also studying the use of the Metatem tool (**Bar**ringer et al.95]to obtain an executable algorithm
specify at a design, implementation-independent **level** which the desired transformations will be. In the
www.egd.igd.fhg.de/veranstaltungen/workshops/egmm96/paper2.ps

Extending Locking Techniques to Improve Concurrent Database.. - Cesar Galindo-Legaria   (Correct)
conflicts remains the same, and only the conflict **table** needs to be extended to include the new lock
multigranularity locking, items are arranged in a **hierarchy** 1 We use the conventional terms for
number of lock requests needed) mechanism for field-**level** locking. Locking of logical structures. Locking
ftp.inria.fr/associations/ERCIM/research_reports/ps/0495R036.ps

Regular Expressions with Nested Levels of Back Referencing Form a .. - Larsen (1997)   (Correct)   (1 citation)
on Theory of Computing, pages 130 -141, 1979. 3] **Bar**endregt, H. P.The Lambda Calculus: Its Syntax and
with Nested **Levels** of Back Referencing Form a **Hierarchy** Kim S. Larsen Odense University y Abstract
Regular Expressions with Nested **Levels** of Back Referencing Form a **Hierarchy** Kim S.
ftp.imada.ou.dk/pub/papers/pp-1997/13.ps.gz

Integration of Reactive Navigation with a Flexible Parallel.. - Thomas Collins (1993)   (Correct)   (2 citations)
designs have emphasized connection across the **hierarchy,** as in the NASA/NBS standard reference model
greater robustness is achieved, even when a higher **level** of deliberative behavior is added. From a
first phase, each robot was to navigate the arena **cluttere**d with obstacles without hitting anything,
ftp.cc.gatech.edu/pub/people/arkin/web-papers/integration.ps.Z

Navigation Modelling in Hypermedia Applications - Daniel Schwabe (1994)   (Correct)
hypermedia applications is the possibility of **navigational** access by the user. Although this type of
ftp.inf.puc-rio.br/pub/docs/techreports/94_42_barbosa.ps.gz

A Design Framework for Hierarchical, Hybrid Control - Lygeros, Godbole, Sastry   (Correct)
scheme will feature some form of multi **level hierarchy,** with lower **levels** dealing with local and
each agent's resource utilization at a lower **level** and discrete controllers resolving inter-agent
Office under grant DAAH 04-95-1-0588 and the **PATH** program, Institute of Transportation Studies,
www.path.berkeley.edu/~lygeros/Publications/../Postscript/TAC_Design.ps

Learning of Compositional Hierarchies for the Modeling of Context .. - Pfleger   (Correct)
with Teknowledge Federal Systems 137-1. Thanks to **Bar**bara Hayes-Roth, Nils Nilsson, David Rumelhart,
in letter perception, and an elegant new symbolic **hierarchy**generation algorithm called Sequitur. The
Hierarchical compositional structure, in which high **level** entities represent aggregations of lower **level**
www.stanford.edu/~kpfleger/copy/publications/CH.learning.ps.gz

Visualizing the World-Wide Web with the Navigational View.. - Mukherjea, Foley (1995)   (Correct)   (33 citations)
Visualizing the World-Wide Web with the **Navigational** View Builder Sougata Mukherjea, James D.
Visualization) where the nodes are listed as a **table** of content of a book. Figure 11 shows a 3d tree
Figure 7: A top view of the structure making the **hierarchy** formed by the abstraction layers apparent. The
ftp.cc.gatech.edu/pub/groups/gvu/tr/95-09.ps.Z

Combining Navigational Planning and Reactive Control - Ali, Goel (1996)   (Correct)   (1 citation)
Combining **Navigational** Planning and Reactive Control Khaled S. Ali
are insufficient for all classes of spatial worlds (**bar**ring toy or imaginary worlds, of course)But if
organizes the neighborhoods in a space-subspace **hierarchy.** A more significant **path**way connects more
www.cc.gatech.edu/grads/a/Khaled.S.Ali/aaai96_workshop.ps.Z

A Three-Level Control Architecture For Autonomous Vehicle.. - Miura, Ito, Shirai (1997)   (Correct)
to the exit. The averaged values are summarized in **Table** 1. With appropriate decisionmaking on the lane
Systems Pp. 706-711, Boston, Ma, Nov. 1997. A Three-**Level** Control Architecture For Autonomous Vehicle
www-cv.ccm.eng.osaka-u.ac.jp/members/jun/psfiles/itsc97.ps.gz

Behavior Hierarchy for Autonomous Mobile Robots.. - Tunstel, Lippincott.. (1997)   (Correct)   (3 citations)
higher fitness is evident for both GP and SSGP. **Table** 1 lists some quantitative details about the best
Behavior **Hierarchy** for Autonomous Mobile Robots: Fuzzy-behavior
which are collectively responsible for necessary **levels** of intelligence. Such a collection of rules can
www.eece.unm.edu/grad/tunstel/papers/acesi.ps

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4	73	((siblings same (hides hiding conceal$4 remov$4) and (index indic$4) with (tabs bar icon node level framc)) and (lowest child$6)) and hierarch$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:38
5	53	(((siblings same (hides hiding conceal$4 remov$4) and (index indic$4) with (tabs bar icon node level frame)) and (lowest child$6)) and hierarch$5) and root and level	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:39
6	31	((((siblings same (hides hiding conceal$4 remov$4) and (index indic$4) with (tabs bar icon node level frame)) and (lowest child$6)) and hierarch$5) and root and level) and (brows$4 navigat$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:48
7	122	indcx with (bar tab) and hierarch$6 and (brows$4 navigat$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:49
8	0	(index with (bar tab) and hierarch$6 and (brows$4 navigat$4)) and siblings same (hides hiding conceal$4 remov$4) and (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:51
9	64	siblings samc (hides hiding conceal$4 remov$4) and display$4 with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:51
10	12	siblings same (hides hiding conceal$4 remov$4) and display$4 with (navigat$4 index) with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 10:55
11	63	siblings same (hides hiding conceal$4 shown display$4 remov$4) and display$4 with (navigat$4 index) with (tabs bar icon node level frame)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:47
12	2	hierarch$5 with level with organiz$4 and clutter$4 and small with display	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:44
13	50	5414809.URPN.	USPAT	2004/06/28 11:36

14	0	hierarch$5 and levels and (tab bar) with index and clutter$4 and small with display	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:45
15	6	hierarch$5 and levels and (tab bar) with index and clutter$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:47
16	163	hierarch$5 and levels and (tab bar) with (index indicies)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:49
17	639	siblings same (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:22
18	0	(hierarch$5 and levels and (tab bar) with (index indicies)) and siblings same (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:48
19	0	hierarch$5 and levels and (tab bar) with (index indicies) and siblings same (hides collaps$4 hiding conceal$4 shown display$4 remov$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:50
20	7	hierarch$5 and levels and (tab bar) with (index indicies) and siblings	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:50
21	131	display$4 with (level node indicies index bar tab) and siblings with (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:57
22	83	(display$4 with (level node indicies index bar tab) and siblings with (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node) and hicrarch$6 and select$4 and (navigat$4 brows$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:58
23	83	((display$4 with (level node indicies index bar tab) and siblings with (hides collaps$4 hiding conccal$4 shown display$4 rcmov$4) and node) and hierarch$6 and select$4 and (navigat$4 brows$4)) and (root sub-node lowest child)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 11:59
24	52	((display$4 with (level node indicies index bar tab) and siblings with (hides collaps$4 hiding conceal$4 shown display$4 rcmov$4) and node) and hierarch$6 and sclect$4 and (navigat$4 brows$4)) and root near5 (node bar tab)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:21
25	99	(travers$4 travel$4) with path and root near5 (node bar tab) and siblings	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:23
26	6	((travers$4 travel$4) with path and root near5 (node bar tab) and siblings) and (sub-node (sub near node))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:26

27	3	((travers$4 travel$4) with path and root near5 (node bar tab) and siblings) and (index indici$4) with (tab bar frame) and represent$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:28
28	3	((travers$4 travel$4) with path and root near5 (node bar tab) and siblings) and (index indici$4 nsvigat$4) with (tab bar frame) and represent$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:28
29	16	((travers$4 travel$4) with path and root near5 (node bar tab) and siblings) and (index indici$4 nsvigat$4 select$4) with (tab bar frame) and represent$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 12:43
30	2	6356920.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:20
31	2	5414809.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:20
32	243	siblings with (hides collaps$4 hiding conceal$4 shown display$4 rcmov$4) and node	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:23
33	65	siblings with (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node and (select$4 travers$4 travel$4) with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:29
34	6	(siblings with (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node and (select$4 travers$4 travel$4) with path) and (show$4 display$4) with (bar tab) with (node index)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:25
35	9	(siblings with (hides collaps$4 hiding conceal$4 shown display$4 remov$4) and node and (select$4 travers$4 travel$4) with path) and (show$4 display$4) with (bar tab) with (node index navigat$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:26
36	13	siblings with (hides collaps$4 hiding conceal$4 remov$4) and node and (select$4 travers$4 travcl$4) with path	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/06/28 13:29